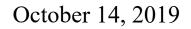
Comparison of Islanding and Synchronization for a Microgrid with Different Converter Controls

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Outline

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➤Work description

Simulation & results.

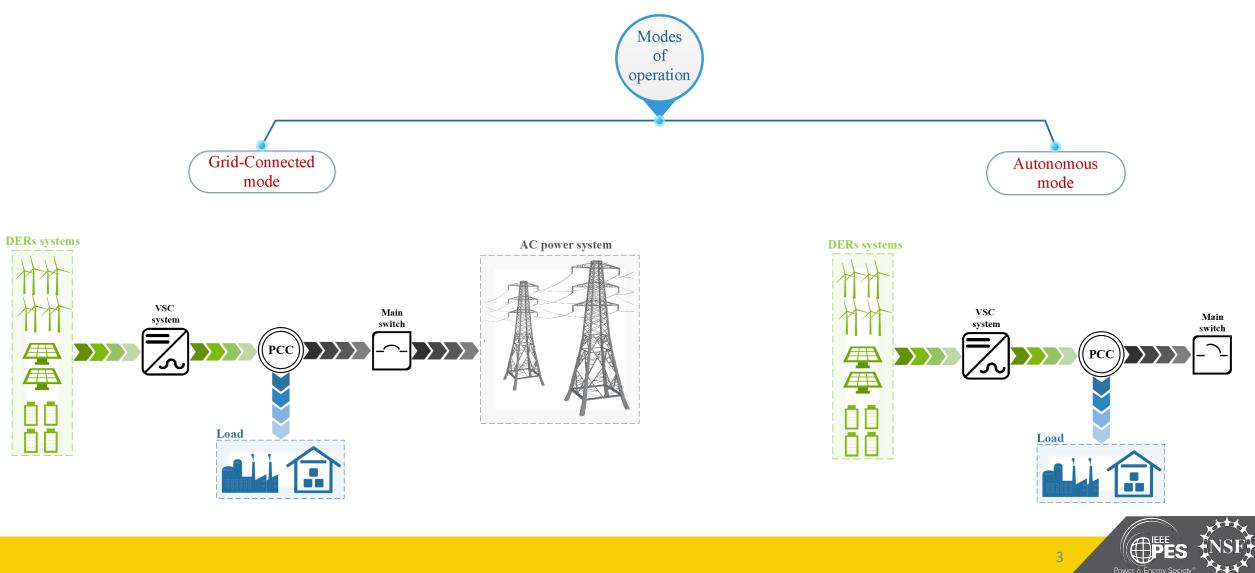
Conclusion

Reference





> Operation modes of microgrids.





Work Description

Main scope:

A comparison of microgrid performance during <u>islanding</u> and <u>synchronization</u> when different voltage source converter (VSC) controls are adopted.

- 1. An overview of VSC controls, namely: 1) grid-following, 2) grid-forming, and 3) grid-supporting.
- 2. A Comparison of microgrid performance is conducted in two testbeds built in MATLAB/SimPowerSystem environment. The two testbeds are compared side by side for their dynamic performance.





Overview of VSC controls

1. Grid-Following VSC:

- Active & reactive power at the PCC are controlled by tuning the <u>converter AC current</u>.
- Also, DC voltage & the PCC voltage could be regulated.
- ➢ It is operated as a <u>current source</u> [7].
- A synchronization mechanism "PLL" is required in order to be *synchronized* with the grid by <u>extracting</u> the grid frequency and PCC voltage angle θ_{PLL} .

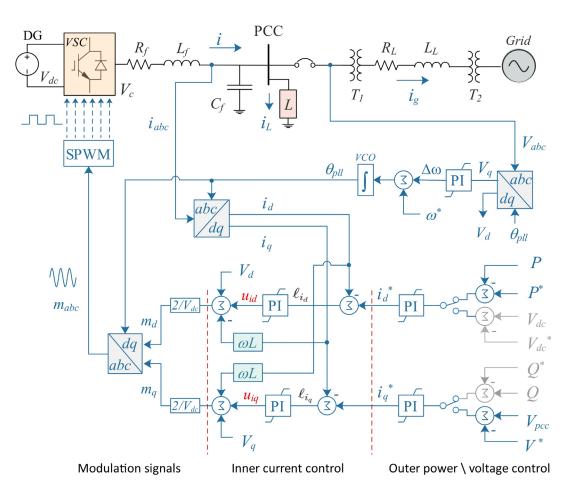


Fig. 1: Schematic control structure of grid-following VSC





Overview of VSC controls

2. Grid-Forming VSC:

- It is operated in MGs as the source of voltage & frequency control by regulating the AC current of the converter.
- ➢ It is operated as an ideal <u>AC voltage source [2]</u>.
- It is similar to the grid-following control structure *except* the outer loop.

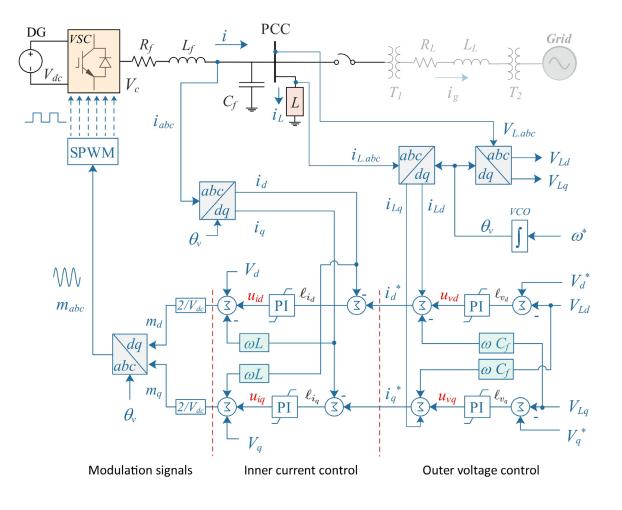


Fig. 2: Schematic control structure of grid-forming VSC.





Overview of VSC controls

3. Grid-Supporting VSC:

- It can operate either in grid-connected mode or autonomous mode.
- No need to re-configuration the converter control.
- Droop controls are implemented on top of a grid-following control structure.
- It can contribute controlling the MG voltage , frequency, active & reactive power at the PCC through its droop design, in both modes:

$$f - f^* = -m(P - P^*)$$

 $V - V^* = -n(Q - Q^*)$

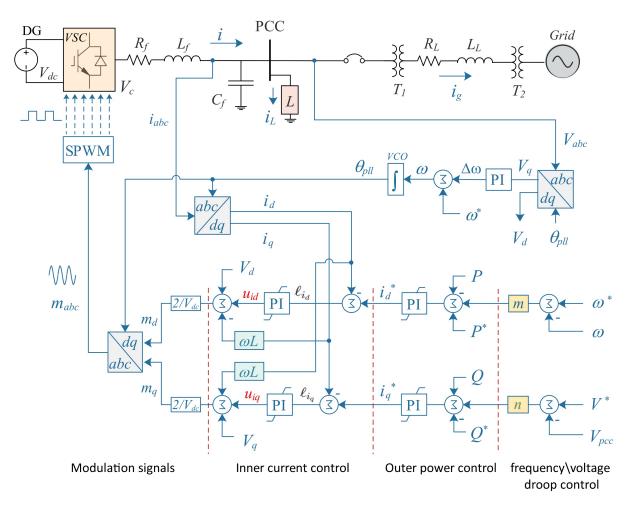


Fig. 3: Schematic control structure of a grid-supporting VSC.



Two testbeds built in MATLAB/SimPowerSystem as follows:

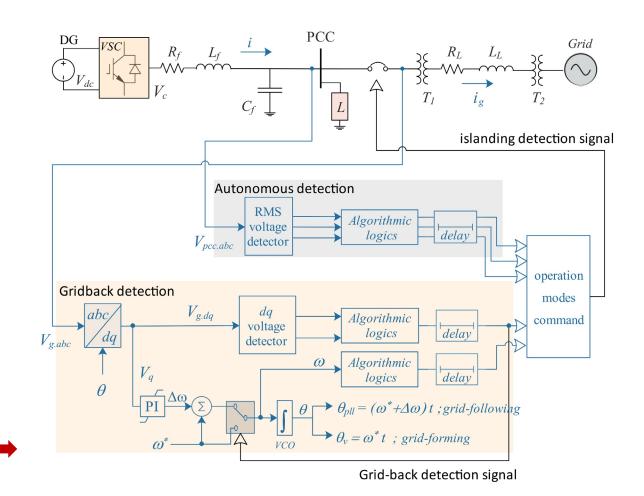
Testbed 1.

A VSC switches back and forth between *grid-following* and *grid-forming* control during islanding and synchronization "grid-connected mode".

Testbed 2.

A VSC works in *grid-supporting* mode regardless of the microgrid operation mode.

Fig.4: an **islanding scheme** and a **grid-back detection** scheme are designed to automatically switch the operation modes of the VSC.







> The testbeds parameters:

	Description	Parameters	Value
Grid side	Transformer 1	T_{I}	400 kVA
			$260 \ V \setminus 25 \ kV$
	Transformer 2	T_2	400 kVA
			$25 \text{ kV} \setminus 120 \text{ kV}$
	Transmission line	R_L , X_L	$0.1 \mathrm{X_L}$, $0.2 \mathrm{pu}$
DG side VSC	Rated power	S_b	400 kVA
	Rated voltage	ac/dc side	260/500 V
	Converter filter	R_{f}	0.156/50 pu
		X_{f}	0.156 pu
	Shunt capacitor	C_{f}	0.25 pu
Load	fixed load	L	300 Kw

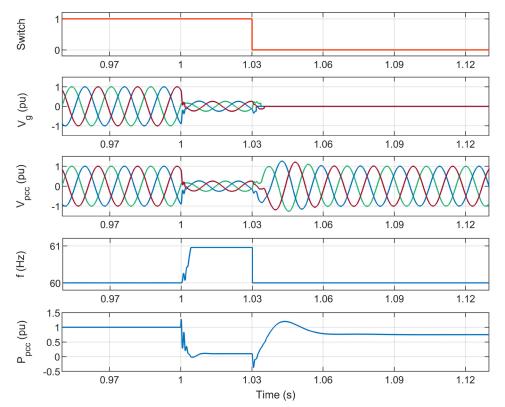
** Reference control settings: $P_{pcc}^* = 1 pu$ $V_{pcc}^* = 1 pu$ $\omega^* = 60 Hz$





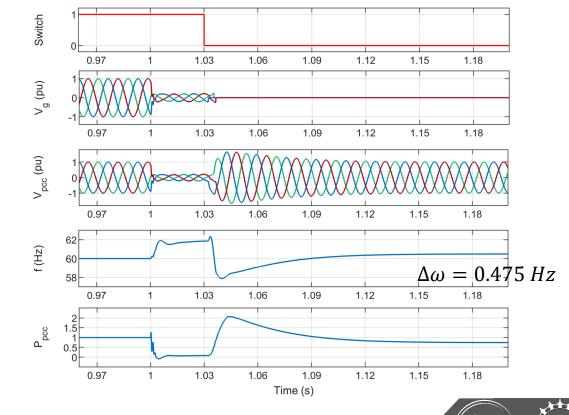
Comparison #1: *Grid-connected* mode to *Autonomous* mode:

- Three phase fault occurs in the transmission line at **1** s.
- Islanding mode is detected after **3** ms.



Testbed # 1: grid-following / grid-forming

Testbed # 2: grid-supporting

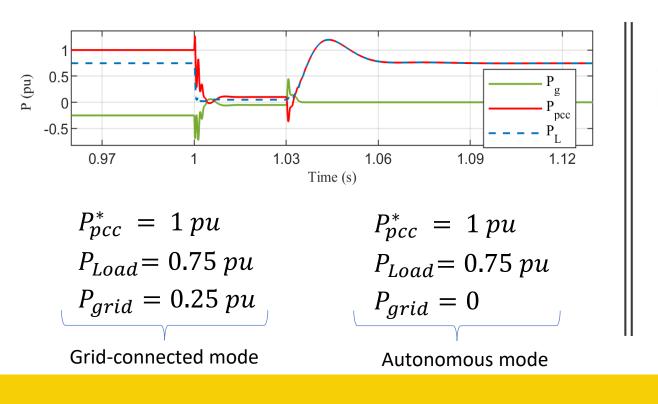


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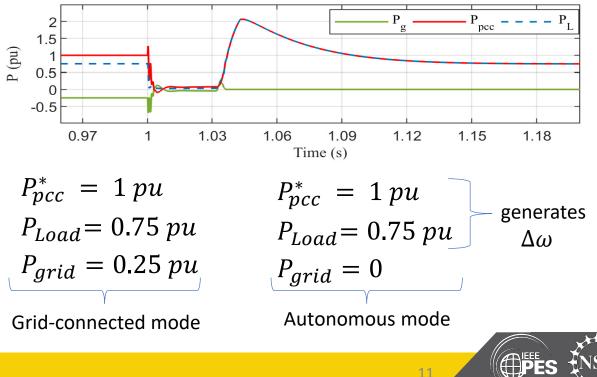
Comparison #1: *Grid-connected* mode to *Autonomous* mode:

- Active power responses: converter output, load, and grid.
- The VSC injects a fixed active power (400 Kw) to the load (300 Kw) and the grid (100 Kw).



Testbed # 1: grid-following / grid-forming

Testbed # 2: grid-supporting



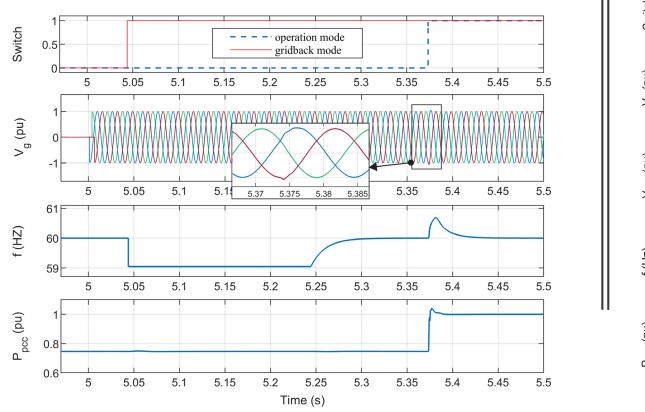


Comparison #2: Autonomous mode to Grid-connected mode :

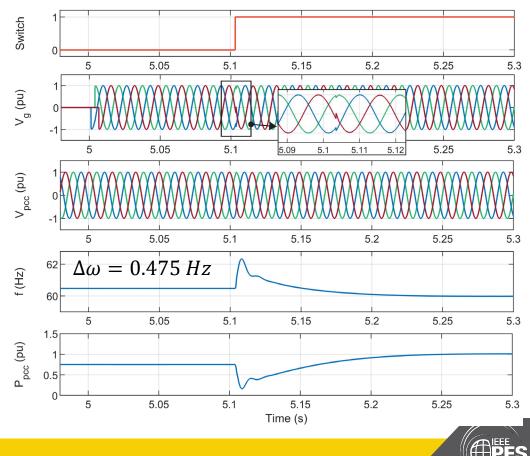
• Three phase fault is cleared at **5** s.

Testbed # 1: grid-following / grid-forming

• The operation mode is switched back to grid-connected mode at **5.37** *s* in testbed 1 and **5.11** *s* in testbed 2.



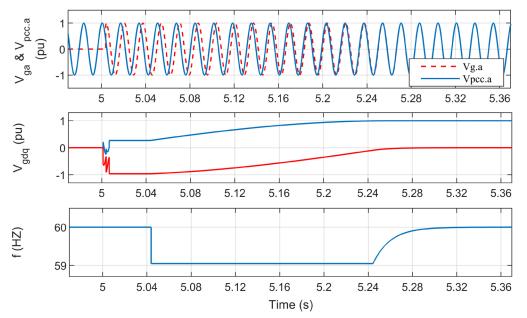
Testbed # 2: grid-supporting



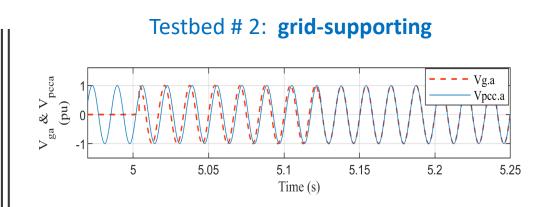


Comparison #2: Autonomous mode to Grid-connected mode :

• Synchronization process between the VSC system and the grid in both testbeds:



Testbed # 1: grid-forming / grid-following



• Frequency is extracted by the PLL in

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both modes of operation.

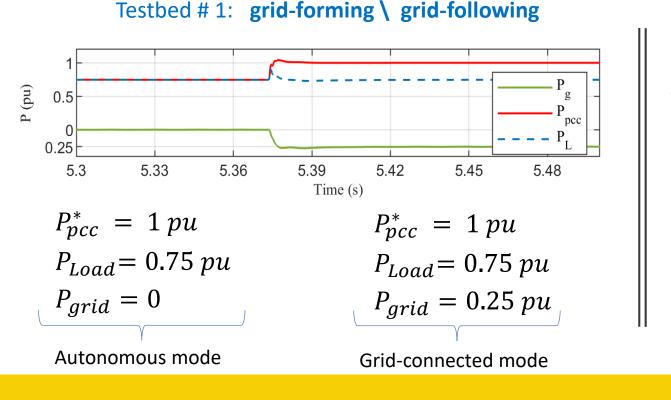
• The Gridback detection signal switches the frequency mode from free-

running frequency by VCO to the PLL frequency (*imposed by the grid*).

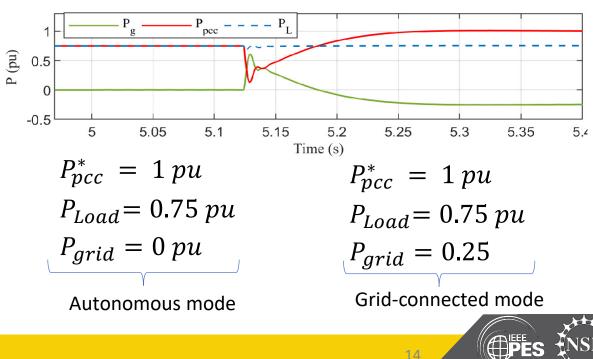


Comparison #2: Autonomous mode Grid-connected mode :

- Active power responses: converter output, load, and grid.
- The VSC injects a fixed active power (400 Kw) to the load (300 Kw) and the grid (100 Kw).









- > The simulation results of switching from one operation to another operation, namely, islanding and re-synchronization, are examined.
- Compared to either the grid-following or grid-forming VSCs, grid-supporting VSC has the advantage of operating in the both operation modes without changing control configuration.
- The droop control has been identified as an effective tool to participate in regulating the frequency, voltage, and power of the microgrid.





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Thank You For Your Attention

Questions ?

